

FREE AP PHYSICS C: MECHANICS

FORMULA SHEET

All the Essential Formulas You Need for Test Day

Unit 1: Kinematics

- Velocity: $\mathbf{v} = d\mathbf{x}/dt$
- Acceleration: $\mathbf{a} = d\mathbf{v}/dt = d^2\mathbf{x}/dt^2$
- Average velocity: $\mathbf{v}_{avg} = \Delta\mathbf{x} / \Delta t$
- Kinematic equations (constant a):
 $\mathbf{v} = \mathbf{v}_0 + \mathbf{a} t$
 $\mathbf{x} = \mathbf{x}_0 + \mathbf{v}_0 t + (1/2) \mathbf{a} t^2$
 $\mathbf{v}^2 = \mathbf{v}_0^2 + 2\mathbf{a}(\mathbf{x} - \mathbf{x}_0)$

Unit 2: Force and Translational Dynamics

- Newton's 2nd Law: $\Sigma\mathbf{F} = m \mathbf{a}$
- Momentum (general form): $\mathbf{F} = d\mathbf{p}/dt$
- Weight: $\mathbf{F}_g = m \mathbf{g}$
- Friction: $\mathbf{f} = \mu \mathbf{N}$
- Hooke's Law: $\mathbf{F}_s = -k \mathbf{x}$

Unit 3: Work, Energy, and Power

- Work (calculus form): $\mathbf{W} = \int \mathbf{F} \cdot d\mathbf{x}$
- Kinetic energy: $\mathbf{KE} = \frac{1}{2} m \mathbf{v}^2$
- Potential energy (gravitational): $\mathbf{U}_g = m \mathbf{g} \mathbf{y}$
- Potential energy (spring): $\mathbf{U}_s = \frac{1}{2} k \mathbf{x}^2$
- Power: $\mathbf{P} = d\mathbf{W}/dt = \mathbf{F} \cdot \mathbf{v}$
- Work-energy theorem: $\mathbf{W}_{net} = \Delta\mathbf{KE}$

Constants

- $g = 9.8 \text{ m/s}^2$
- $\pi \approx 3.1416$
- $G = 6.67 \times 10^{-11} \text{ N}\cdot\text{m}^2/\text{kg}^2$
- $M_e = 5.97 \times 10^{24} \text{ kg}$ (mass of Earth)
- $R_e = 6.37 \times 10^6 \text{ m}$ (radius of Earth)

Unit 4: Linear Momentum

- Momentum: $\mathbf{p} = m \mathbf{v}$
- Impulse: $\mathbf{J} = \int \mathbf{F} dt = \Delta\mathbf{p}$
- Conservation of momentum:
 $\Sigma\mathbf{p}_{initial} = \Sigma\mathbf{p}_{final}$
- Center of mass: $\mathbf{r}_{cm} = (\Sigma m_i \mathbf{r}_i) / (\Sigma m_i)$

Unit 5: Torque and Rotational Dynamics

- Torque: $\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F} = r F \sin\theta$
- Net torque: $\Sigma\boldsymbol{\tau} = I \boldsymbol{\alpha}$
- Moment of inertia: $I = \Sigma m_i r_i^2$
- Angular momentum: $\mathbf{L} = I \boldsymbol{\omega}$
- Torque relation: $\boldsymbol{\tau} = d\mathbf{L}/dt$
- Rolling without slipping: $\mathbf{v} = \boldsymbol{\omega} \mathbf{r}$

Unit 6: Energy and Momentum of Rotating Systems

- Rotational kinetic energy: $\mathbf{KE}_{rot} = \frac{1}{2} I \boldsymbol{\omega}^2$
- Total kinetic energy (rolling):
 $\mathbf{KE}_{total} = \frac{1}{2} M \mathbf{v}^2 + \frac{1}{2} I \boldsymbol{\omega}^2$
- Angular momentum:
 $\mathbf{L} = \mathbf{r} \times \mathbf{p}$ (particle), $\mathbf{L} = I \boldsymbol{\omega}$ (rigid body)
- Conservation of angular momentum:
 $\mathbf{L}_{initial} = \mathbf{L}_{final}$

Unit 7: Oscillations

- Hooke's Law: $\mathbf{F} = -k \mathbf{x}$
- Period of spring: $\mathbf{T} = 2\pi \sqrt{(m / k)}$
- Period of pendulum (small angle):
 $\mathbf{T} = 2\pi \sqrt{(L / g)}$
- SHM general solution: $\mathbf{x}(t) = \mathbf{A} \cos(\boldsymbol{\omega}t + \boldsymbol{\varphi})$
- Angular frequency:
 $\boldsymbol{\omega} = \sqrt{(k/m)}$ (spring), $\boldsymbol{\omega} = \sqrt{(g/L)}$ (pendulum)

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